

Intact stability calculation

The mass and centre of gravity of the whole system are input for the intact stability calculation. For this tutorial a very simplified stability calculation is used. The only input value that is required is the moment of area inertia of the waterline area.

- Create a new class in the Knowledge Browser alongside the others that you have made so far: `Intact stability calculation`.
- Create the following parameters in the **Knowledge Browser**:

Parameter name	Dimension	Determined by	Reference	In Class
BM	[m]	<code>USR: User or system/equation</code>	Distance between center of buoyancy and metacenter	<code>Intact stability calculation</code>
GM	[m]	<code>USR: User or system/equation</code>	Metacentric height	<code>Intact stability calculation</code>
KB	[m]	<code>USR: User or system/equation</code>	Distance between keel and center of buoyancy	<code>Intact stability calculation</code>
KG	[m]	<code>USR: User or system/equation</code>	Distance between keel and center of gravity	<code>Intact stability calculation</code>
Moment_of_Inertia	[m^4]	<code>USR: User or system/equation</code>	Moment of inertia of the water plane area, For this tutorial give a rough estimate	<code>Intact stability calculation</code>

- Include the following parameters in entity `Intact stability calculation`: Loa,Boa,BM, COGX, COGY, COGZ, Displacement, GM, KB, KG , Moment_of_Inertia, Rho, and T_design.
- Create the following relations (either entity relations or normal relations, it does not matter here):

`Loa = ENTITY#(xx).Loa` where "xx" is the QEntityID value of entity Main Dimensions.

`Boa = ENTITY#(xx).Boa` where "xx" is the QEntityID value of entity Main Dimensions.

`GM = KB + BM - KG`

`BM = Moment_of_Inertia / (Displacement/Rho)`

`KG = COGZ`

`KB = 0.7*T_design`

`T_design = ENTITY#(xx).T_design` where "xx" is the QEntityID value of entity Hydrostatics.

`Displacement = ENTITY#(xx).Mass` where "xx" is the QEntityID value of entity Mass calculation.

`COGX = ENTITY#(xx).COGX` where "xx" is the QEntityID value of entity Mass calculation.

`COGY = ENTITY#(xx).COGY` where "xx" is the QEntityID value of entity Mass calculation.

`COGZ = ENTITY#(xx).COGZ` where "xx" is the QEntityID value of entity Mass calculation.

`Rho = ENTITY#(xx).Rho` where "xx" is the QEntityID value of entity Hydrostatics.

- To show computed values set attribute `@SHOW` on QEntityData.

Workbase

The screenshot shows the Workbase software interface. On the left, there is a tree view of a dataset named "Dataset[Tutorial1]". The tree includes nodes for QTaxonomy, Ship configurator, Ship design, Mass calculation, Intact stability calculation (which is selected and highlighted in blue), Data to Excel, and Data to Word report. At the top, there are buttons for Local, (Internal) Name only, All, Data input, and Stop input. On the right, there is a table with columns for Parameter, Value, and Dimension.

Parameter	Value	Dimension
Loa	-	m
BM	-	m
Boa	-	m
COGX	-	m
COGY	-	m
COGZ	-	m
Displacement	-	t
GM	-	m
KB	-	m
KG	-	m
Moment_of_Inertia	-	m^4
QEntityData	Text/Telitab	Str
QEntityID	4	m
QEntityName	\$Intact stability calculation	Str
Rho	(No value)	t/m^3
T_design	-	m

[Back to content](#) | << Previous | Next >>